

# Multi-Soliton Solution of NLSE using Darboux Transformation.

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## Introduction

We shall obtain multi-soliton solutions of Nonlinear Schrodinger Equation (NLE) by using Darboux transformation (DT).

- ❖ In 1882, G. Darboux proposed a transformation method to solve the **linear differential equations**, known as **DT**.
- ❖ Latter on V. B. Matveev and M. A. Salle introduced a method to solve integrable **NLEs** with the help of **Lax pair (linear system)**, to determine the **multi-soliton solutions** by using known solutions.
- ❖ Widely used to get multi-soliton solutions of KdV, mKdV, NLS & Sine Gordon equations. Etc.
- ❖ Darboux Transformation can also be used to find breather and Rogue wave solutions after few modifications.

## Method: Darboux Transformation

We derive Darboux Transformation for one dimensional NLSE with constant coefficients P and Q, as given below.

$$i\Psi_t + P\Psi_{xx} - 2Q\Psi|\Psi|^2 = 0$$

Its corresponding linear system (lax pair) of AKNS scheme is

$$\Psi_x = U\Psi, \quad \text{and} \quad \Psi_t = V\Psi, \quad \text{where}$$

$$U = \begin{pmatrix} -\frac{i}{2}\lambda & \sqrt{\frac{Q}{P}}r \\ \sqrt{\frac{Q}{P}}q & \frac{i}{2}\lambda \end{pmatrix} = U_0 + \lambda U_1$$

$$V = \begin{pmatrix} \frac{iP}{2}\lambda^2 + iQqr & -\sqrt{QP}r\lambda - i\sqrt{QP}r_x \\ -\sqrt{QP}q\lambda + i\sqrt{QP}q_x & -\frac{iP}{2}\lambda^2 - iQqr \end{pmatrix}$$

$$V = V_0 + \lambda V_1 + \lambda^2 V_2$$

- ❖ Zero curvature condition  $U_t - V_x + [U, V] = 0$  verifies that linear system is compatible to the Nonlinear system.
- ❖ We get system of NLSE (2 equations), which reduces to NLSE when  $q=r^*$ .

$$iq_t + Pq_{xx} - 2Qq|q|^2 = 0$$

## N-Fold Darboux Transformation

Darboux Transformation is a special gauge transformation, as

$$\Psi[N] = T(x, t, \lambda)\Psi$$

Then transformed linear system is

$$\Psi_x[N] = U[N]\Psi[N] \quad \text{Where} \quad U[N] = (T_x + TU)T^{-1}$$

$$\text{and} \quad \Psi_t[N] = V[N]\Psi[N] \quad \text{Where} \quad V[N] = (T_t + TV)T^{-1}$$

$$T(x, t, \lambda) = \begin{pmatrix} A(x, t, \lambda) & B(x, t, \lambda) \\ C(x, t, \lambda) & D(x, t, \lambda) \end{pmatrix} = \sum_{j=0}^N a_j(x, t)\lambda^j$$

$$a_j = \begin{pmatrix} A_j(x, t) & B_j(x, t) \\ C_j(x, t) & D_j(x, t) \end{pmatrix} \quad (j = 0, 1, 2, \dots, N-1) \quad \text{and} \quad a_N = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Since  $\det T(x, t, \lambda)$  has  $2N$  zeros  $\lambda_k$  and the coefficient of  $\lambda^N$  is an identity matrix and from transformation equation we get

$$\begin{aligned} \sum_{j=0}^{N-1} [A_j + \beta_k B_j] \lambda_k^j &= -\lambda_k^N & \text{Where} \\ \sum_{j=0}^{N-1} [D_j + \alpha_k C_j] \lambda_k^j &= -\lambda_k^N & \beta_k = \frac{1}{\alpha_k} = \frac{\phi_2(\lambda_k) - b_k \psi_2(\lambda_k)}{\phi_1(\lambda_k) - b_k \psi_1(\lambda_k)} \end{aligned}$$

From these two equation, we can get values of A, B, C and D of matrix T by using Cramer's rule.

From equation  $U[N] = (T_x + TU)T^{-1}$  and  $V[N] = (T_t + TV)T^{-1}$  We get new protentional in form of  $q[N]$  and  $r[N]$ .

$$r[N] = r + i\sqrt{\frac{Q}{P}}B_{N-1} \quad \text{and} \quad q[N] = q + i\sqrt{\frac{Q}{P}}C_{N-1}$$

We can obtain the values of  $B_{N-1}$  and  $C_{N-1}$  by using Cramer's rule for any value of N. Hence, we obtain N Soliton Solutions of NLSE in the form of  $q[N]$  and  $r[N]$ .

By introducing the **reduction condition**  $q[N] = r^*[N]$  and following assumptions proposed by Neugebauer.

$$\lambda_{2j} = \lambda_{2j-1}^*, \quad \alpha_{2j} = -\frac{1}{\alpha_{2j-1}^*}, \quad \beta_{2j} = -\frac{1}{\beta_{2j-1}^*}$$

## Result: Multi-Soliton Solutions

The matrix given below is multi-soliton solution for NLSE when seed solution  $q=0$ .

For any value of N, it gives exact soliton solution

$$q[N] = q + i\sqrt{\frac{P}{Q}} \begin{vmatrix} 1 & \alpha_1 & \lambda_1 & \lambda_1 \alpha_1 & \dots & \lambda_1^{N-1} & \lambda_1^N \\ 1 & -(\alpha_1^*)^{-1} & \lambda_1^* & -\lambda_1^* (\alpha_1^*)^{-1} & \dots & \lambda_1^{*N-1} & \lambda_1^{*N} \\ \vdots & \vdots & \vdots & \vdots & \dots & \vdots & \vdots \\ 1 & -(\alpha_N^*)^{-1} & \lambda_N^* & -\lambda_N^* (\alpha_N^*)^{-1} & \dots & \lambda_N^{*N-1} & \lambda_N^{*N} \end{vmatrix}$$

## Result: Single Soliton Solution

- ❖ For **N=1**
- ❖ We choose **q=0** as **seed solution**, then equation of multi-soliton solutions will become.

$$q[1] = q + i\sqrt{\frac{P}{Q}} \begin{vmatrix} 1 & \lambda_1 \\ 1 & \alpha_1 \\ 1 & -(\alpha_1^*)^{-1} \end{vmatrix} \quad \alpha_k = \frac{-1}{b_k} \exp(-i\lambda_k x + iP\lambda_k^2 t)$$

$$q[1] = \sqrt{\frac{P}{Q}} \eta_1 \operatorname{sech}(X_1) \exp(iY_1)$$

$$b_1 = \exp[\mu_1 + i\sigma_1]$$

$$\lambda_1 = \zeta_1 + i\eta_1$$

$$Y_1 = \zeta_1 x - P(\zeta_1^2 - \eta_1^2)t + \sigma_1$$

$$X_1 = \eta_1 x - 2P\zeta_1 \eta_1 t - \mu_1$$

## Conclusion

- ❖ To find the N-Fold Darboux transformation of NLSE, we have applied a method proposed by G. Neugebauer using Lax pairs in matrix form.
- ❖ The Lax pairs provided the compatible linearized system for the nonlinear Schrödinger equation.
- ❖ We have derived N-fold DT of NLSE system by using gauge transformation and reduction technique.
- ❖ Later, we have obtained the multi-soliton solutions by choosing
  - Zero solution as initial condition.
  - Complex eigenvalue.
- ❖ The single soliton solution contains product of sec-hyperbolic and exponential function that appears as an envelope soliton structure

## Future Work

- ❖ We shall derive N-fold Darboux transformations of nonlinear soliton equations using different approaches of Darboux transformation and find the multi-soliton solutions of different plasma models.
- ❖ To observe the spontaneous modulation of the wave, we shall find the multi-rogue wave solutions using Darboux transformation and modified Darboux transformation.
- ❖ The graphical descriptions will be shown for different plasma models.
- ❖ We shall find the periodic multi-rogue wave solutions of different NLEEs.

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